Applications of Network Flow CS 3AC3

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Max-flow and min-cut applications

Max-flow and min-cut are widely applicable problem-solving model.

- Data mining.
- Open-pit mining.
- Bipartite matching.
- Network reliability.
- Baseball elimination.
- Image segmentation.
- Network connectivity.
- Distributed computing.
- · Security of statistical data.
- Egalitarian stable matching.
- Network intrusion detection.
- Multi-camera scene reconstruction.
- Sensor placement for homeland security.
- Many, many, more.



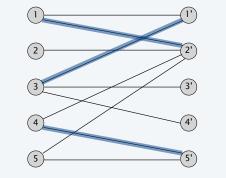
liver and hepatic vascularization segmentation

Bipartite matching

L

Def. A graph *G* is bipartite if the nodes can be partitioned into two subsets *L* and *R* such that every edge connects a node in *L* to one in *R*.

Bipartite matching. Given a bipartite graph $G = (L \cup R, E)$, find a max cardinality matching.



matching: 1-2', 3-1', 4-5'

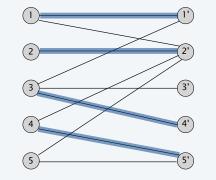
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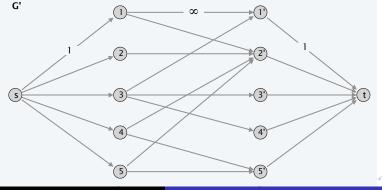


matching: 1-1', 2-2', 3-4', 4-5'

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Bipartite matching: max flow formulation

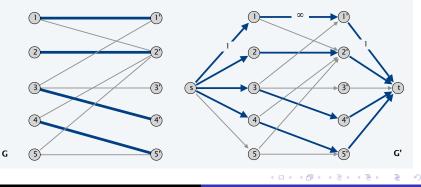
- Create digraph $G' = (L \cup R \cup \{s, t\}, E')$.
- Direct all edges from *L* to *R*, and assign infinite (or unit) capacity.
- Add source *s*, and unit capacity edges from *s* to each node in *L*.
- Add sink *t*, and unit capacity edges from each node in *R* to *t*.



Max flow formulation: proof of correctness

Theorem. Max cardinality of a matching in G = value of max flow in G'. Pf. \leq

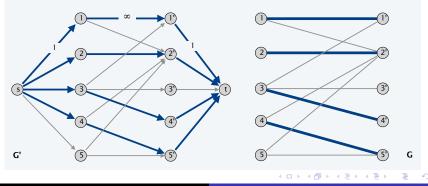
- Given a max matching *M* of cardinality *k*.
- Consider flow *f* that sends 1 unit along each of *k* paths.
- *f* is a flow, and has value *k*. •



Max flow formulation: proof of correctness

Theorem. Max cardinality of a matching in G = value of max flow in G'. Pf. \geq

- Let *f* be a max flow in *G*' of value *k*.
- Integrality theorem \Rightarrow k is integral and can assume f is 0-1.
- Consider M = set of edges from L to R with f(e) = 1.
 - each node in L and R participates in at most one edge in M
 - |M| = k: consider cut $(L \cup s, R \cup t)$ •



Def. Given a graph G = (V, E) a subset of edges $M \subseteq E$ is a perfect matching if each node appears in exactly one edge in M.

Q. When does a bipartite graph have a perfect matching?

Structure of bipartite graphs with perfect matchings.

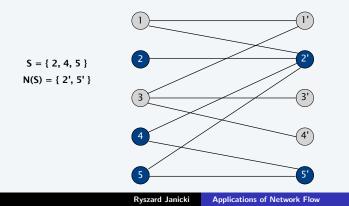
- Clearly we must have |L| = |R|.
- What other conditions are necessary?
- What conditions are sufficient?

Perfect matching in a bipartite graph

Notation. Let *S* be a subset of nodes, and let N(S) be the set of nodes adjacent to nodes in *S*.

Observation. If a bipartite graph $G = (L \cup R, E)$ has a perfect matching, then $|N(S)| \ge |S|$ for all subsets $S \subseteq L$.

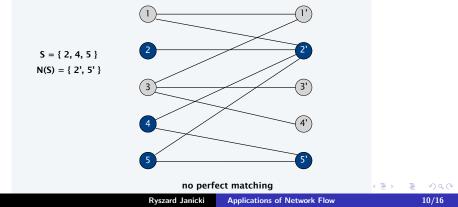
Pf. Each node in *S* has to be matched to a different node in *N*(*S*).



Hall's Theorem

Theorem. Let $G = (L \cup R, E)$ be a bipartite graph with |L| = |R|. *G* has a perfect matching iff $|N(S)| \ge |S|$ for all subsets $S \subseteq L$.

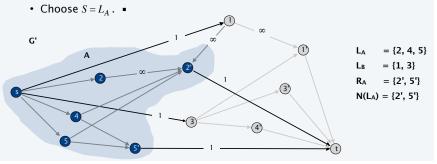
Pf. \Rightarrow This was the previous observation.



Proof of Hall's theorem

Pf. \leftarrow Suppose G does not have a perfect matching.

- Formulate as a max flow problem and let (A, B) be min cut in G'.
- By max-flow min-cut theorem, cap(A, B) < |L|.
- Define $L_A = L \cap A$, $L_B = L \cap B$, $R_A = R \cap A$.
- $\bullet \ cap(A,B) \ = \ |L_B| + |R_A|.$
- Since min cut can't use ∞ edges: $N(L_A) \subseteq R_A$.
- $|N(L_A)| \le |R_A| = cap(A, B) |L_B| < |L| |L_B| = |L_A|.$



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Theorem

The Ford-Fulkerson algorithm solves the bipartite matching problem in O(mn) time, where n is the number of nodes and m is the number of edges.

Airline scheduling.

- Complex computational problem faced by nation's airline carriers.
- · Produces schedules that are efficient in terms of:
 - equipment usage, crew allocation, customer satisfaction
 - in presence of unpredictable issues like weather, breakdowns
- One of largest consumers of high-powered algorithmic techniques.

"Toy problem."

- Manage flight crews by reusing them over multiple flights.
- Input: set of *k* flights for a given day.
- Flight *i* leaves origin *o_i* at time *s_i* and arrives at destination *d_i* destination at time *f_i*.
- Minimize number of flight crews.

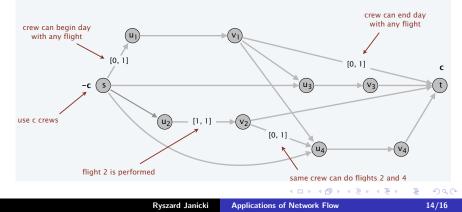
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Airline scheduling

Circulation formulation. [to see if c crews suffice]

- For each flight *i*, include two nodes *u_i* and *v_i*.
- Add source *s* with demand *-c*, and edges (*s*, *u_i*) with capacity 1.
- Add sink t with demand c, and edges (v_i, t) with capacity 1.
- For each *i*, add edge (u_i, v_i) with lower bound and capacity 1.
- if flight *j* reachable from *i*, add edge (v_i, u_j) with capacity 1.



Theorem. The airline scheduling problem can be solved in $O(k^3 \log k)$ time. Pf.

- k = number of flights.
- *c* = number of crews (unknown).
- *O*(*k*) nodes, *O*(*k*²) edges.
- At most *k* crews needed.
 - \Rightarrow solve lg k circulation problems. \leftarrow binary search for optimal value c*
- Value of the flow is between 0 and k.

 \Rightarrow at most *k* augmentations per circulation problem.

• Overall time = $O(k^3 \log k)$.

Remark. Can solve in $O(k^3)$ time by formulating as minimum flow problem.

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Airline scheduling: postmortem

Remark. We solved a toy problem.

Real-world problem models countless other factors:

- Union regulations: e.g., flight crews can only fly certain number of hours in given interval.
- Need optimal schedule over planning horizon, not just one day.
- Deadheading has a cost.
- Flights don't always leave or arrive on schedule.
- Simultaneously optimize both flight schedule and fare structure.

Message.

- Our solution is a generally useful technique for efficient reuse of limited resources but trivializes real airline scheduling problem.
- Flow techniques useful for solving airline scheduling problems (and are widely used in practice).
- Running an airline efficiently is a very difficult problem.

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