

COMP SCI and SFWR ENG 4-6TE3, and CES 723
Midterm Exam Solution (Fall 2006)

Oleksandr Romanko

October 27, 2006

1. Consider the function:

$$f(x_1, x_2) = (x_1 - 2x_2)^2 e^{x_1 + x_2}$$

- (a) (i) Give the gradient and the Hessian of $f(x_1, x_2)$.
- (ii) Give the second-order Taylor series expansion of $f(x_1, x_2)$ at the point $x^0 = (1, -1)^T$.
- (b) Prove that the function $f(x)$ is not convex.
- (c) Make a step with Newton's method from the point $x^0 = (1, -1)^T$ when you minimize the function $f(x)$.
- (d) Examine if the point $x = (-2, 1)^T$ is a local/global minimum of $f(x)$ by using its gradient/Hessian information.
- (e) Give the directional derivative of the function $f(x)$ at the point $x^0 = (1, -1)^T$ in the direction $s = (2, 1)^T$. Examine if this direction is a descent or an ascent direction.

10p

Solution

a. The gradient and the Hessian of the function $f(x_1, x_2)$ are:

$$\begin{aligned} \nabla f(x_1, x_2) &= \begin{pmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \end{pmatrix} = \begin{pmatrix} 2(x_1 - 2x_2)e^{x_1 + x_2} + (x_1 - 2x_2)^2 e^{x_1 + x_2} \\ -4(x_1 - 2x_2)e^{x_1 + x_2} + (x_1 - 2x_2)^2 e^{x_1 + x_2} \end{pmatrix} = \\ &= \begin{pmatrix} (2(x_1 - 2x_2) + (x_1 - 2x_2)^2)e^{x_1 + x_2} \\ (-4(x_1 - 2x_2) + (x_1 - 2x_2)^2)e^{x_1 + x_2} \end{pmatrix} \\ \nabla^2 f(x_1, x_2) &= \begin{pmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 \partial x_2} \\ \frac{\partial^2 f}{\partial x_1 \partial x_2} & \frac{\partial^2 f}{\partial x_2^2} \end{pmatrix} = \\ &= \begin{pmatrix} 2 + 4(x_1 - 2x_2) + (x_1 - 2x_2)^2 & -4 - 2(x_1 - 2x_2) + (x_1 - 2x_2)^2 \\ -4 - 2(x_1 - 2x_2) + (x_1 - 2x_2)^2 & 8 - 8(x_1 - 2x_2) + (x_1 - 2x_2)^2 \end{pmatrix} e^{x_1 + x_2} \end{aligned}$$

The second order Taylor series expansion of the function $f(x_1, x_2)$ at the point x^0 is:

$$f(x) = f(x^0) + \nabla f(x^0)^T (x - x^0) + \frac{1}{2} (x - x^0)^T \nabla^2 f(x^0) (x - x^0).$$

In our case, for $x^0 = (x_1^0, x_2^0)^T = (1, -1)^T$ we get:

$$\begin{aligned} f(x_1, x_2) &= f(x_1^0, x_2^0) + \nabla f(x_1^0, x_2^0)^T \begin{pmatrix} x_1 - x_1^0 \\ x_2 - x_2^0 \end{pmatrix} \\ &\quad + \frac{1}{2} \begin{pmatrix} x_1 - x_1^0 \\ x_2 - x_2^0 \end{pmatrix}^T \nabla^2 f(x_1^0, x_2^0) \begin{pmatrix} x_1 - x_1^0 \\ x_2 - x_2^0 \end{pmatrix} \\ &= 9 + \begin{pmatrix} 15 \\ -3 \end{pmatrix}^T \begin{pmatrix} x_1 - 1 \\ x_2 + 1 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} x_1 - 1 \\ x_2 + 1 \end{pmatrix}^T \begin{pmatrix} 23 & -1 \\ -1 & -7 \end{pmatrix} \begin{pmatrix} x_1 - 1 \\ x_2 + 1 \end{pmatrix} \\ &= -9x_1 - 10x_2 + \frac{23}{2}x_1^2 - x_1x_2 - \frac{7}{2}x_2^2. \end{aligned}$$

b. At the point $x^0 = (2, 0)^T$, the principal minor

$$\frac{\partial^2 f}{\partial x_2^2} = (8 - 8(x_1 - 2x_2) + (x_1 - 2x_2)^2)e^{x_1+x_2} = (8 - 8 \cdot 2 + 2^2)e^2 = -4e^2 < 0$$

which means that the Hessian $\nabla^2 f(x_1, x_2)$ of the function $f(x_1, x_2)$ is not positive-semidefinite at that point. So, $f(x_1, x_2)$ is not a convex function.

c. Apply a full Newton step for $f(x_1, x_2) = (x_1 - 2x_2)^2 e^{x_1+x_2}$ with $x^0 = (1, -1)^T$.

$$x^1 = x^0 - (\nabla^2 f(x^0))^{-1} \nabla f(x^0)$$

$$\nabla f(x) = \begin{pmatrix} (2(x_1 - 2x_2) + (x_1 - 2x_2)^2)e^{x_1+x_2} \\ (-4(x_1 - 2x_2) + (x_1 - 2x_2)^2)e^{x_1+x_2} \end{pmatrix}$$

$$\nabla^2 f(x) = \left(\begin{pmatrix} 2 & -4 \\ -4 & 8 \end{pmatrix} + (x_1 - 2x_2) \begin{pmatrix} 4 & -2 \\ -2 & -8 \end{pmatrix} + (x_1 - 2x_2)^2 \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \right) e^{x_1+x_2}$$

$$\nabla f(x^0) = \begin{pmatrix} 15 \\ -3 \end{pmatrix} \quad \nabla^2 f(x^0) = \begin{pmatrix} 2 & -4 \\ -4 & 8 \end{pmatrix} + 3 \begin{pmatrix} 4 & -2 \\ -2 & -8 \end{pmatrix} + 9 \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 23 & -1 \\ -1 & -7 \end{pmatrix}$$

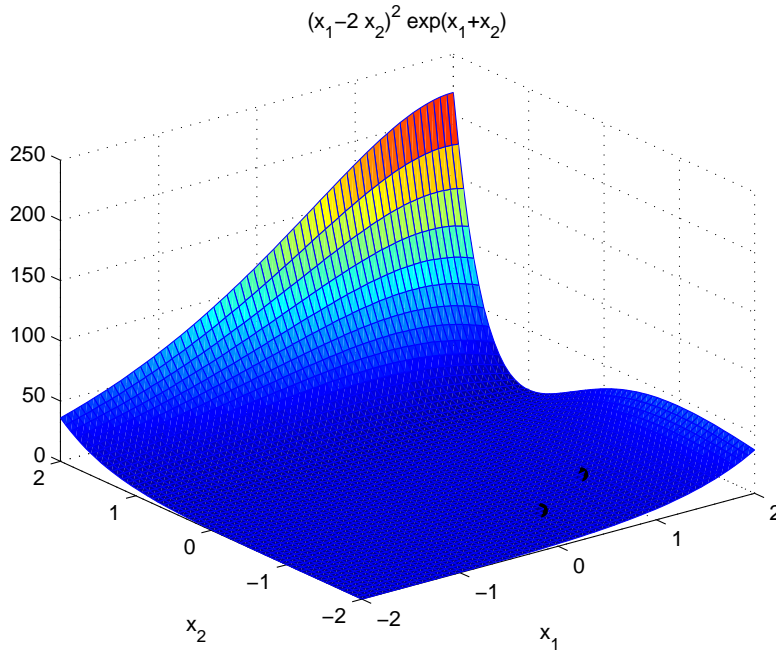
Instead of inverting matrix $\nabla^2 f(x^0)$, which is costly, we can solve the system of equations. Note that if we want to compute $y = A^{-1}b$, we can solve the system of equations $Ay = b$ to find y . In our case, we can solve the system of equations $\nabla^2 f(x^0)y = \nabla f(x^0)$ to get $y = (\nabla^2 f(x^0))^{-1} \nabla f(x^0)$:

$$\begin{pmatrix} 23 & -1 \\ -1 & -7 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} 15 \\ -3 \end{pmatrix} \implies y_1 = \frac{2}{3}, y_2 = \frac{1}{3}.$$

Finally,

$$x^1 = x^0 - (\nabla^2 f(x^0))^{-1} \nabla f(x^0) = \begin{pmatrix} 1 \\ -1 \end{pmatrix} - \begin{pmatrix} \frac{2}{3} \\ \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} \\ -\frac{4}{3} \end{pmatrix}$$

$$f(x_1) = 3.3109 < f(x_0) = 9$$



- d. The point $x = (-2, 1)^T$ is not a local/global minimum of $f(x)$ because the gradient at that point is not equal to zero:

$$\nabla f(x) = \begin{pmatrix} (2(x_1 - 2x_2) + (x_1 - 2x_2)^2)e^{x_1+x_2} \\ (-4(x_1 - 2x_2) + (x_1 - 2x_2)^2)e^{x_1+x_2} \end{pmatrix} = \begin{pmatrix} 8e^{-1} \\ 32e^{-1} \end{pmatrix}.$$

- e. Directional derivative of the function $f(x)$ at the point $(1, -1)^T$ in the direction $s = (2, 1)^T$.
The directional derivative is:

$$\delta f(x, s) = \nabla f(x)^T s = \begin{pmatrix} (2(x_1 - 2x_2) + (x_1 - 2x_2)^2)e^{x_1+x_2} \\ (-4(x_1 - 2x_2) + (x_1 - 2x_2)^2)e^{x_1+x_2} \end{pmatrix}^T s = (15, -3) \begin{pmatrix} 2 \\ 1 \end{pmatrix} = 27 > 0$$

This is an ascent direction.

2. Give a sequence that has sub-linear converges to -1 , and prove its convergence rate.

3p

Solution Sequence that converges to -1 sub-linearly. Consider the sequence $\alpha_k = \frac{1}{k} - 1$. This sequence converges to -1 when $k \rightarrow \infty$. Let us take $p = 1$, then $\lim_{k \rightarrow \infty} \frac{1/(k+1)}{(1/k)^1} = \lim_{k \rightarrow \infty} \frac{k}{k+1} = 1$. In addition, $\lim_{k \rightarrow \infty} \frac{1/(k+1)}{(1/k)^{1+\epsilon}} = \lim_{k \rightarrow \infty} \frac{k k^\epsilon}{k+1} = \lim_{k \rightarrow \infty} k^\epsilon = \infty \forall \epsilon > 0$. So, the order of convergence is $p^* = 1$. Moreover, $\beta = \lim_{k \rightarrow \infty} \frac{|\alpha_{k+1} - \alpha|}{|\alpha_k - \alpha|} = \lim_{k \rightarrow \infty} \frac{1/(k+1)}{1/k} = 1$ which implies sub-linear convergence.

3. Consider the function $f(x_1, x_2) = (x_1 - 2x_2)^2 e^{x_1+x_2}$.

- (a) Let $x^0 = (2, 0)^T$, $x^1 = (1, -1)^T$, $x^2 = (-1, -1)^T$. Apply one cycle of the Nelder-Mead simplex algorithm to minimize the function when $\alpha = 0.5$, $\beta = 2/3$ and $\gamma = 2$.

- (b) Make a line-search step by using the Goldstein-Armijo method from the point $x^0 = (-1, 1)^T$ in the direction $s = (1, -1)^T$, when $\mu_1 = 0.2$, $\mu_2 = 0.9$ and $\alpha_0 = 0.8$. Let the multiplication factor be 2, if the step-length has to be increased; 0.5 if it has to be decreased; and when the step-length interval is identified, use bi-section to find the Goldstein-Armijo step-length.

8p

Solution

- a. Sort the points in the order of ascending function value

$$f(x^0) = f(-1, -1) = e^{-2} = 0.1353 \leq f(x^1) = f(1, -1) = 9 \leq f(x^2) = f(2, 0) = 4e^2 = 29.5562;$$

$$\bar{x} = \frac{x^0 + x^1}{2} = (0, -1)^T; x^r = \bar{x} + (\bar{x} - x^2) = (-2, -2)^T;$$

$$f(x^r) = 4e^{-4} = 0.0733 < f(x^0);$$

$$x^e = \bar{x} + \gamma(\bar{x} - x^2) = (-4, -3)^T; f(x^e) = 4e^{-7} = 0.0036 < f(x^r);$$

$$\text{Drop } x^2 = (2, 0)^T \text{ and add } x^e = (-4, -3)^T.$$

- b. Goldstein-Armijo line-search step from the point $x^0 = (-1, 1)^T$ in the direction $s^0 = (1, -1)^T$ when $\mu_1 = 0.2$, $\mu_2 = 0.9$, $\alpha_0 = 0.8$:

$$f(x^0) = f(-1, 1) = 9,$$

$$f(x^1) = f(x^0 + \alpha_0 s^0) = f(x^0 + 0.8s^0) = f(-0.2, 0.2) = 0.36.$$

$$\nabla f(x) = \begin{pmatrix} (2(x_1 - 2x_2) + (x_1 - 2x_2)^2)e^{x_1+x_2} \\ (-4(x_1 - 2x_2) + (x_1 - 2x_2)^2)e^{x_1+x_2} \end{pmatrix}.$$

$$\text{Check if } -\alpha_0\mu_1\nabla f(x^0)^T s^0 \leq f(x^0) - f(x^1) \leq -\alpha_0\mu_2\nabla f(x^0)^T s^0:$$

$$-\alpha_0\mu_1\nabla f(x^0)^T s^0 = -0.8 \cdot 0.2 \cdot (3, 21)(1, -1)^T = 2.88$$

$$-\alpha_0\mu_2\nabla f(x^0)^T s^0 = -0.8 \cdot 0.9 \cdot (3, 21)(1, -1)^T = 12.96$$

So, $2.88 \leq f(x^0) - f(x^1) = 8.64 \leq 12.96$. The Goldstein-Armijo conditions are satisfied \implies the step-length α_0 should be accepted.

4. Which of the following statements is true/false. Give a one-sentence justification of your answer.

- (a) Every convex function is monotone non-decreasing.
- (b) The minimum of two convex functions is convex.
- (c) The cost of a step of the steepest descent algorithm is $O(n)$ arithmetic operations.
- (d) The Trust Region algorithms requires the Hessian to be positive definite.
- (e) The Hessian of a convex function has only real eigenvalues.
- (f) The intersection of convex sets is convex.
- (g) The bi-section method (for zero finding in 1-dimension) converge quadratically to find the root of the function x^3 .
- (h) The function $e^{(x^2)}$ is a convex function.
- (i) The relative interior of a nonempty convex set is closed.
- (j) The superlinear convergence is faster than linear convergence.

10p

Solution

- a. False. A function f is monotonically non-decreasing if, whenever $x \leq y$, then $f(x) \leq f(y)$. For example, $f(x) = x^2$ is not monotonically non-decreasing on $(-\infty, 0)$, so, a convex function is not necessarily monotonically non-decreasing.
 - b. False. Epigraph of the minimum of convex functions is a union of the functions epigraphs, but union of convex sets (functions epigraphs) is not necessarily convex.
 - c. False. The cost of a step of the steepest descent algorithm is $O(n)$ plus line search as at each step we need to compute a search direction $s^k = -\nabla f(x^k)$ which is the gradient of dimension n and perform the line search.
 - d. False. The Hessian is not required to be positive definite as by adding αI to it we can make the resulting matrix positive definite.
 - e. True. The Hessian of a function is symmetric and, so, has only real eigenvalues.
 - f. True. If we take two points inside the intersection, the line connecting them still belongs to the intersection (as the line belongs to each set).
 - g. False. Bisection method converges linearly with the convergence rate $\beta = \frac{1}{2}$ for every function.
 - h. True. As exponential function is convex nondecreasing, by using composition rules we can say that a function $e^{g(x)}$ is convex if $g(x)$ is convex. The quadratic function $g(x) = x^2$ is convex and, so, $e^{(x^2)}$ is convex as well.
 - i. False. The relative interior of a non-empty circle is open.
 - j. True. Though they have the same order of convergence, the superlinear convergence is faster than all linear as it has lower rate of convergence.
-

5. Consider the function $f(x_1, x_2) = 18x_1 + x_2^2 + (x_1 - 2x_2)^2$. Apply the Fletcher-Reeves conjugate gradient method to find the minimum of the function $f(x_1, x_2)$ starting from the point $x^0 = (1, 0)^T$.

4p

Solution

- a. Fletcher-Reeves conjugate gradient algorithm with $x^0 = (1, 0)^T$. We have quadratic function of the form $f(x) = \frac{1}{2}x^T Ax - b^T x$, where

$$A = \begin{pmatrix} 2 & -4 \\ -4 & 10 \end{pmatrix}, \quad b = \begin{pmatrix} -18 \\ 0 \end{pmatrix}, \quad x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$\nabla f(x) = \begin{pmatrix} 18 + 2(x_1 - 2x_2) \\ 2x_2 - 4(x_1 - 2x_2) \end{pmatrix} = \begin{pmatrix} 18 + 2x_1 - 4x_2 \\ -4x_1 + 10x_2 \end{pmatrix}.$$

Iteration 1:

$$\text{Initial point: } x^0 = \begin{pmatrix} 1 \\ 0 \end{pmatrix},$$

$$\nabla f(x^0) = \begin{pmatrix} 20 \\ -4 \end{pmatrix},$$

$$s^0 = -\nabla f(x^0) = \begin{pmatrix} -20 \\ 4 \end{pmatrix}.$$

We use exact line search to find $x^1 = \arg \min(x^0 + \lambda_0 s^0)$:

$$\lambda_0 = -\frac{(s^0)^T \nabla f(x^0)}{(s^0)^T A s^0} = 0.26.$$

So,

$$x^1 = x^0 + \lambda_0 s^0 = \begin{pmatrix} 1 \\ 0 \end{pmatrix} + 0.26 \begin{pmatrix} -20 \\ 4 \end{pmatrix} = \begin{pmatrix} -4.2 \\ 1.04 \end{pmatrix}.$$

$$f(x^1) = -35.08 < f(x^0) = 19.$$

Iteration 2:

$$\nabla f(x^1) = \begin{pmatrix} 5.44 \\ 27.2 \end{pmatrix},$$

$$s^1 = -\nabla f(x^1) + \frac{\|\nabla f(x^1)\|^2}{\|\nabla f(x^0)\|^2} s^0 = \begin{pmatrix} -5.44 \\ -27.2 \end{pmatrix} + \frac{769.4336}{416} \begin{pmatrix} -20 \\ 4 \end{pmatrix} = \begin{pmatrix} -42.4320 \\ -19.8016 \end{pmatrix}.$$

We can check that s^0 and s^1 are conjugate, i.e., $(s^0)^T A s^1 = 0$.

Using exact line search to find $x^2 = \arg \min(x^1 + \lambda_1 s^1)$, we get:

$$\lambda_1 = -\frac{(s^1)^T \nabla f(x^1)}{(s^1)^T A s^1} = 0.9615.$$

$$x^2 = x^1 + \lambda_1 s^1 = \begin{pmatrix} -4.2 \\ 1.04 \end{pmatrix} + 0.9615 \begin{pmatrix} -42.4320 \\ -19.8016 \end{pmatrix} = \begin{pmatrix} -45 \\ -18 \end{pmatrix}.$$

We can check that x^2 is the optimal solution as $\nabla f(x^2) = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$.

THE END