Admissibility of solution estimators to stochastic optimization problems

Amitabh Basu

Joint Work with Tu Nguyen and Ao Sun

2nd Discrete Optimization and Machine Learning, RIKEN Center for Advanced Intelligence Program, Tokyo, Japan, July 2019

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 $\boldsymbol{\xi}$ is a random variable taking values in \mathbb{R}^m

 $\min_{x\in X} \mathbb{E}_{\xi}[F(x,\xi)]$

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Example:

Supervised Machine Learning: One sees samples $(z, y) \in \mathbb{R}^n \times \mathbb{R}$ of labeled data from some (joint) distribution, and one aims to find a function $f \in \mathcal{F}$ in a hypothesis class \mathcal{F} that minimizes the expected loss $\mathbb{E}_{(z,y)}[\ell(f(z), y)]$, where $\ell : \mathbb{R} \times \mathbb{R} \to \mathbb{R}_+$ is some loss function. Then $X = \mathcal{F}$, m = n + 1, $\xi = (z, y)$, and

 $F(f,(z,y)) = \ell(f(z),y).$

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Example:

(News) Vendor Problem: (News) Vendor buys some units of a product (newspapers) from supplier at cost of c > 0 dollars/unit; at most u units available. Stochastic demand for product. Product sold at price p > c dollars/unit. End of day, vendor can return unsold product to supplier at r < c dollars/unit. Find number of units to buy to maximize (minimize) the expected profit (loss).

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 $F(x,\xi) = cx - p\min\{x,\xi\} - r\max\{x-\xi,0\}.$

Solving the problem

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$$\min_{x \in X} \quad \frac{1}{n} \sum_{i=1}^{n} F(x, \xi^{i})$$

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Stochastic optimizers call this sample average approximation (SAA); machine learners call this empirical risk minimization.

Concrete Problem

 $F(x,\xi) = \xi^T x$

 $X \subseteq \mathbb{R}^d$ is a compact set (e.g., polytope, integer points in a polytope). So m = d.

 $\xi \sim N(\mu, \Sigma).$

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Solve the problem only given access to *n* i.i.d. samples of ξ . Important: μ is unknown.

Sample Average Approximation (SAA):

$$\min_{x \in X} \quad \frac{1}{n} \sum_{i=1}^{n} F(x, \xi^{i}) = \min_{x \in X} \quad \overline{\xi}^{T} x$$

where $\overline{\xi} := \frac{1}{n} \sum_{i=1}^{n} \xi^{i}$.

A quick tour of Statistical Decision Theory

Set of states of nature, modeled by a set Θ .

Set of possible actions to take, modeled by \mathcal{A} .

In a particular state of nature $\theta \in \Theta$, the performance of any action $a \in A$, is evaluated by a loss function $\mathcal{L}(\theta, a)$. Goal: choose action to minimize loss.

(Partial/Incomplete) Information about θ is obtained through a random variable y taking values in a sample space χ . The distribution of y depends on the particular state of nature θ , denoted by P_{θ} .

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Decision Rule: Takes $y \in \chi$ as input and reports an action $a \in A$. Denote by $\delta : \chi \to A$.

 $X \subseteq \mathbb{R}^d$ is a compact set. $\xi \sim N(\mu, I)$.

$$\min_{x \in X} \mathbb{E}_{\xi}[F(x,\xi)] = \min_{x \in X} \mathbb{E}_{\xi}[\xi^{T}x] = \min_{x \in X} \mu^{T}x$$

States of Nature: $\Theta = \mathbb{R}^d = \{ \text{all possible } \mu \in \mathbb{R}^d \}.$

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 $\mathcal{L}(\bar{\mu}, \bar{x}) = \mathbb{E}_{\xi \sim \mathcal{N}(\bar{\mu}, I)}[F(\bar{x}, \xi)] - \min_{x \in \mathcal{X}} \mathbb{E}_{\xi \sim \mathcal{N}(\bar{\mu}, I)}[F(x, \xi)]$

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Decision Rule: $\delta : \chi \to X$.

Our problem cast as statistical decision problem $X \subseteq \mathbb{R}^d$ is a compact set. $\xi \sim N(\mu, I)$.

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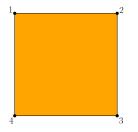
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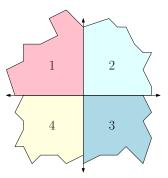
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Sample Space: $\chi = \mathbb{R}^d \times \mathbb{R}^d \times \dots \times \mathbb{R}^d$ Decision Rule: $\delta : \chi \to X$.

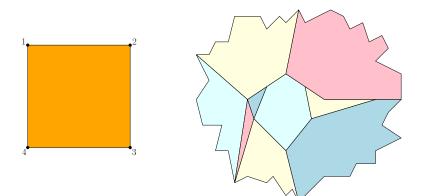
SAA: $\delta(\xi^1, \ldots, \xi^n) \in \arg \max\{\overline{\xi}^T x : x \in X\}$

Decision Rules

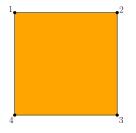




Decision Rules



Decision Rules





States of nature Θ , Actions \mathcal{A} , Loss function $\mathcal{L} : \Theta \times \mathcal{A} \to \mathbb{R}$, Sample space χ with distributions $\{P_{\theta} : \theta \in \Theta\}$.

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 $R_{\delta}(\theta) := \mathbb{E}_{y \sim P_{\theta}} [\mathcal{L}(\theta, \delta(y))]$

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We say that a decision rule δ' dominates a decision rule δ if $R_{\delta'}(\theta) \leq R_{\delta}(\theta)$ for all $\theta \in \Theta$, and $R_{\delta'}(\theta^*) < R_{\delta}(\theta^*)$ for some $\theta^* \in \Theta$.

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If a decision rule δ is not dominated by any other decision rule, we say that δ is admissible. Otherwise, it is inadmissible.

Is the Sample Average Approximation (SAA) rule admissible?

Stochastic optimization setup:

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Want to solve with access to *n* i.i.d. samples of ξ . Statistical decision theory view: $\xi \sim N(\mu, I)$; states of nature $\Theta = \mathbb{R}^m = \{ \text{all possible } \mu \in \mathbb{R}^m \}.$ Set of actions $\mathcal{A} = X$, Sample space $\chi = \underbrace{\mathbb{R}^d \times \mathbb{R}^d \times \ldots \times \mathbb{R}^d}_{n \text{ times}}$

Loss function

 $\mathcal{L}(\bar{\mu},\bar{x}) = \mathbb{E}_{\xi \sim \mathcal{N}(\bar{\mu},I)} [F(\bar{x},\xi)] - \min_{x \in X} \mathbb{E}_{\xi \sim \mathcal{N}(\bar{\mu},I)} [F(x,\xi)]$

Given a decision rule $\delta : \chi \to X$, the risk of δ

 $R_{\delta}(\mu) := \mathbb{E}_{\xi^1, \dots, \xi^n} [\mathcal{L}(\mu, \delta(\xi^1, \dots, \xi^n))]$

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Sample Average Approximation (SAA) can be inadmissible!!

Inadmissibility of SAA: Stein's Paradox

$$\mathcal{L}(\bar{\mu},\bar{x}) = \mathbb{E}_{\xi \sim \mathcal{N}(\bar{\mu},l)} [F(\bar{x},\xi)] - \min_{x \in X} \mathbb{E}_{\xi \sim \mathcal{N}(\bar{\mu},l)} [F(x,\xi)]$$

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$$F(x,\xi) = \|x - \xi\|^2, \qquad X = \mathbb{R}^d, \qquad \xi \sim N(\mu, I).$$
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$$\min_{x \in \mathbb{R}^d} \mathbb{E}_{\xi \sim N(\mu, I)}[\|x - \xi\|^2] = \min_{x \in \mathbb{R}^d} \|x - \mu\|^2 + \mathbb{V}[\xi]$$

Optimal solution: $x(\bar{\mu}) = \bar{\mu}$, Optimal value: $\mathbb{V}[\xi] = d$.

 $\mathcal{L}(\bar{\mu},\bar{x})=\|\bar{x}-\bar{\mu}\|^2.$

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Sample Average Approximation (SAA):

$$\min_{\mathbf{x}\in\mathbb{R}^d} \frac{1}{n} \sum_{i=1}^n \|\mathbf{x}-\xi^i\|^2$$
$$\delta_{SAA}(\xi^1,\ldots,\xi^n) = \overline{\xi} := \sum_{i=1}^n \xi^i.$$

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$$\min_{x \in \mathbb{R}^d} \mathbb{E}_{\xi \sim N(\mu, I)} [\|x - \xi\|^2]$$

Generalized to arbitrary convex quadratic function with uncertain linear term in Davarnia and Cornuéjols 2018. Follow-up work from a Bayesian perspective in Davarnia, Kocuk and Cornuéjols 2018. A class of problems with no Stein's paradox

THEOREM Basu-Nguyen-Sun 2018

Consider the problem of optimizing an uncertain linear objective $\xi \sim N(\mu, I)$ over a fixed compact set $X \subseteq \mathbb{R}^d$:

 $\min_{x \in X} \mathbb{E}_{\xi \sim N(\mu, I)}[\xi^T x]$

The Sample Average Approximation (SAA) rule is admissible.



Sufficient Statistic: $\mathcal{P} = \{P_{\theta} : \theta \in \Theta\}$ family of distributions for r.v. y in sample space χ . Sufficient statistic for this family is a function $T : \chi \to \tau$ such that the conditional probability P(y|T = t) does not depend on θ .

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FACT:

$$\chi = \underbrace{\mathbb{R}^d \times \ldots \times \mathbb{R}^d}_{n \text{ times}}, \ \mathcal{P} = \{\underbrace{\mathcal{N}(\mu, l) \times \ldots \times \mathcal{N}(\mu, l)}_{n \text{ times}} : \mu \in \mathbb{R}^d\},\$$

i.e., $(\xi^1, \ldots, \xi^n) \in \chi$ are i.i.d samples from the normal distribution $N(\mu, I)$. Then $T(\xi^1, \ldots, \xi^n) = \overline{\xi} := \frac{1}{n} \sum_{i=1}^n \xi^i$ is a sufficient statistic for \mathcal{P} .

For any decision rule δ , define the function

$$F(\mu) = R_{\delta}(\mu) - R_{\delta_{SAA}}(\mu).$$

Suffices to show that there exists $\hat{\mu} \in \mathbb{R}^d$ such that $F(\hat{\mu}) > 0$.

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Use a fact from probability theory that for any Lebesgue integrable function $f : \mathbb{R}^n \to \mathbb{R}^d$, the map

$$\mu \ \mapsto \ \mathbb{E}_{y \in \mathcal{N}(\mu, \Sigma)} \left[f(y) \right] := \int_{\mathbb{R}^d} f(y) \exp\left(-\frac{1}{2}(y-\mu)^T \Sigma^{-1}(y-\mu)\right) dy$$

has derivatives of all orders and these can be computed by taking the derivative under the integral sign.

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- METATHEOREM (from Gérard Cornuéjols): Admissible if and only if feasible region is bounded !?

THANK YOU !

Questions/Comments ?