

# Logical Properties



## Logical Properties

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**Concepts:** modeling properties that refer to states

**Models:** **fluent** - characterization of abstract state  
based on action sets  
**fluent linear temporal logic**

## Introduction

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- ◆ Temporal logic due to Pnueli (1977) is a popular means to describe behavioural properties in logic.
- ◆ Use propositions to describe selected variable states at particular points in program executions.
- ◆ Realized as the **assert** construct in Java.
- ◆ Challenge: How to refer to states in an LTS model based on actions or events?
- ◆ Artifact: Introduce **fluents** to describe abstract state of LTS models.
- ◆ Express both safety and liveness properties in fluent propositions.

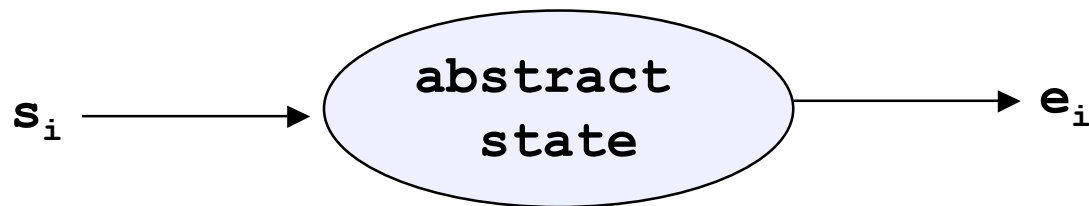
*Pnueli, A. (1997). The Temporal Logic of Programs. Proc. of the 18<sup>th</sup> IEEE Symposium on the Foundations of Computer Science, Oct/Nov 1997, pp. 46-57.*

## Fluents

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fluent  $FL = \langle \{s_1, \dots, s_n\}, \{e_1, \dots, e_n\} \rangle$  initially  $B$  defines a fluent  $FL$  that is initially true if the expression  $B$  is true and initially false if the expression  $B$  is false.  $FL$  becomes true when any of the initiating (or starting) actions  $\{s_1, \dots, s_n\}$  occur and false when any of the terminating (or ending) actions  $\{e_1, \dots, e_n\}$  occur. If the term **initially**  $B$  is omitted then  $FL$  is initially false. The same action may not be used as both an initiating and terminating action.

- ◆ A fluent  $\langle \{s_1, \dots, s_n\}, \{e_1, \dots, e_n\} \rangle$  describes an abstract state that is entered by executing any of the actions in  $\{s_1, \dots, s_n\}$ , and exited by executing any of the actions in  $\{e_1, \dots, e_n\}$ .



# Fluents

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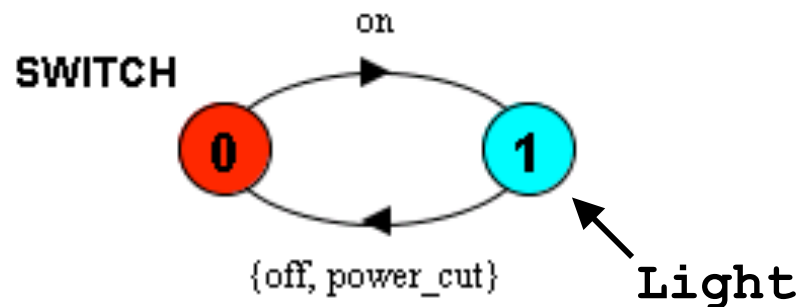
`const False = 0`

`const True = 1`

`fluent LIGHT = <{on}, {off, power_cut}>`  
`initially false`

◆ SWITCH is initially not at state Light.

`fluent DARK = <{off, power_cut}, on>`  
`initially true`



## Fluent Family

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```
const False = 0
```

```
const True = 1
```

```
fluent LIGHT[i:1..2] = <on[i], {off[i], power_cut}>
```

is equivalent to defining two fluents:

```
const False = 0
```

```
const True = 1
```

```
fluent LIGHT1 = <on[1], {off[1], power_cut}>
```

```
fluent LIGHT2 = <on[2], {off[2], power_cut}>
```

## Fluent Expressions

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- ◆ Fluents can be composed using normal logical operators: &&, ||, !, ->, <->, forall, exists
- ◆ If the light is on, power is also on:

```
fluent LIGHT = <on,off>
fluent POWER = <power_on, power_off>
LIGHT -> POWER
```

- ◆ All lights are on:

```
forall[i:1..2] LIGHT[i]
```

- ◆ At least one light is on:

```
exists[i:1..2] LIGHT[i]
```

## Action Fluent

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- ◆ An action fluent  $a$  defines the state after an action  $a$  has been executed but before the execution of other actions including the silent action  $\tau$ .
- ◆ Suppose  $\alpha$  is the alphabet of a system:

`fluent a = <a,  $\alpha \cup \{\tau\}$  - a >`

- ◆ bell rings once the room is lit:

`bellring && LIGHT`

- ◆ Note that action `bell_ring` must not belong to the terminating action set of fluent `LIGHT`




## Safety Properties: Mutual Exclusion

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```
const N = 2
range Int = 0..N
SEMAPHORE (I=0) = SEMA[I],
SEMA[v: Int]   = (up->SEMA[v+1]
                  |when (v>0) down->SEMA[v-1]
                  ).
```

```
LOOP = (mutex.down->enter->exit->mutex.up->LOOP) .
||SEMADEMO = (p[1..N]:LOOP
             || {p[1..N]}::mutex:SEMAPHORE(2)).
```

fault 

```
fluent CRITICAL[i:1..N] = <p[i].enter, p[i].exit>
```

- ◆ Two processes are in their critical sections simultaneously:

```
CRITICAL[1] && CRITICAL[2]
```

## Safety Properties: Mutual Exclusion

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The linear temporal logic formula  $[\ ]F$  - always  $F$  - is true if and only if the formula  $F$  is true at the current instant and at all future instants.

- ◆ No two processes can be at critical sections simultaneously:

```
assert MUTEX = [\ ]! (CRITICAL[1] && CRITICAL[2])
```

- ◆ LTSA compiles the assert statement into a property process:

```
property MUTEX = (p[i:1..N].enter -> p[i].exit -> MUTEX  
) .
```

# Safety Properties: Mutual Exclusion

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Trace to property violation in MUTEX:

p.1.mutex.down

p.1.enter                   CRITICAL.1

p.2.mutex.down           CRITICAL.1

p.2.enter                   CRITICAL.1 && CRITICAL.2

- ◆ General expression of the mutual exclusion property for N processes:

```
assert MUTEX_N(N=2) = []!(exists [i:1..N-1]
(CRITICAL[i] && CRITICAL[i+1..N] ))
```

## Safety Properties: Oneway in Single-Lane Bridge

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```
const N = 2 // number of each type of car
range ID= 1..N // car identities
```

```
fluent RED[i:ID] = <red[i].enter, red[i].exit>
fluent BLUE[i:ID] = <blue[i].enter, blue[i].exit>
```

```
assert ONEWAY = []!(exists[i:ID] RED[i]
                    && exists[j:ID] BLUE[j])
```

◆ Abbreviating `exists[i:R] FL[i]` as `FL[R]`

```
assert ONEWAY = []!(RED[ID] && BLUE[ID])
```

## Single Lane Bridge - safety property ONEWAY

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The fluent proposition is more concise as compared with the property process ONEWAY. This is usually the case where a safety property can be expressed as a relationship between abstract states of a system.

```
property ONEWAY = (red[ID].enter -> RED[1]
                  | blue.[ID].enter -> BLUE[1]
                  ),
RED[i:ID] = (red[ID].enter -> RED[i+1]
            | when(i==1) red[ID].exit -> ONEWAY
            | when(i>1) red[ID].exit -> RED[i-1]
            ), //i is a count of red cars on the bridge
BLUE[i:ID]= (blue[ID].enter-> BLUE[i+1]
            | when(i==1)blue[ID].exit -> ONEWAY
            | when( i>1)blue[ID].exit -> BLUE[i-1]
            ). //i is a count of blue cars on the bridge
```

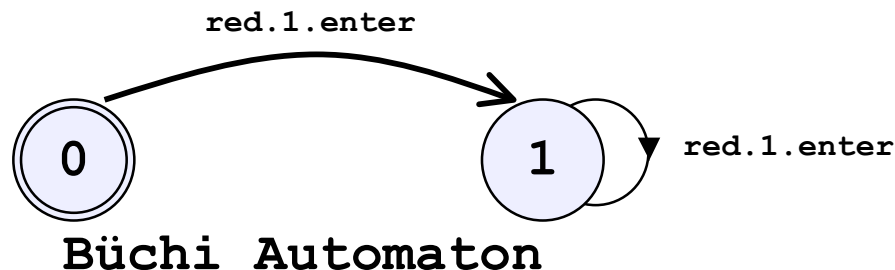
# Liveness Properties

The linear temporal logic formula  $\langle \rangle F$  - eventually  $F$  - is true if and only if the formula  $F$  is true at the current instant or at some future instant.

- ◆ First red car must eventually enter the bridge:

```
assert FIRSTRED =  $\langle \rangle$ red[1].enter
```

- ◆ To check the liveness property, LTSA transforms the negation of the assert statement in terms of a Büchi automaton.
- ◆ A Büchi automaton recognizes an infinite trace if that trace passes through an acceptance state infinitely often.



## Liveness Properties: Progress Properties

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- ◆ Compose the Büchi automaton and the original system.
- ◆ Search for acceptance state in strong connected components.
- ◆ Failure of the search implies no trace can satisfy the Buchi automaton.
- ◆ It validates that the assert property holds.
  
- ◆ Red and blue cars enter the bridge infinitely often.

```
assert REDCROSS = forall [i:ID] []<>red[i].enter
assert BLUECROSS = forall [i:ID] []<>blue[i].enter
assert CROSS    = (REDCROSS && BLUECROSS)
```

## Liveness Properties: Response Properties

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- ◆ If a red car enters the bridge, it should eventually exit.
- ◆ It does not stop in the middle or fall over the side!

```
assert REDEXIT = forall [i:ID]
  [] (red[i].enter -> <>red[i].exit)
```

- ◆ Such kind of properties is sometimes termed "response" properties, which follows the form:

```
[] (request-> <>reply)
```

- ◆ This form of liveness property cannot be specified using the progress properties discussed earlier.



## Liveness Properties:

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```
assert MUTEX_N(N=2) = []!(exists [i:1..N-1]
  (CRITICAL[i] && CRITICAL[i+1..N] )) //safety

assert EXIT_N(N=2) = forall[i:1..N]
  [](p[i].enter -> <>p[i].exit //liveness

assert MUTEX_LIVE(N=2) = MUTEX_N(N) && EXIT_N(N)
```

- ◆ EXIT\_N asserts that a process entering the critical section will eventually exit.

## Fluent Linear Temporal Logic (FLTL)

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- ◆ There are five operators in FLTL
  - Always []
  - Eventually <>
  - Until U
  - Weak until W
  - Next time X
- ◆ Amongst the five operators, always [] and eventually <> are the two most commonly used ones.
- ◆ Until, Weak until and Next time allows complex relation between abstract states.

## FLTL: Until U

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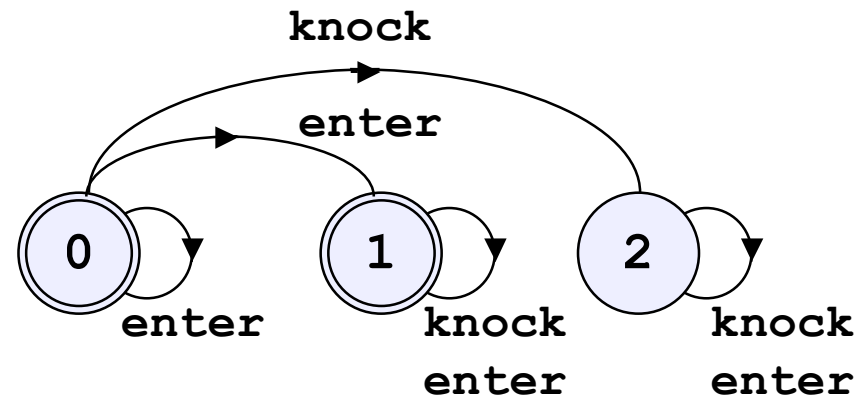
The linear temporal logic formula  $p \text{ U } q$  -  $p$  until  $q$  - is true if and only if  $q$  is true at the current instant or  $p$  is true until some future instant where  $q$  is true.

- ◆ We should not enter a room before knocking  
`assert POLITE = (!enter U knock)`
- ◆ The proposition also mandates that a knock action should eventually happen
- ◆ The proposition is not purely a safety property

# FLTL: Until U

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Büchi automaton of POLITE



- ◆ Note that if a knock never occurs, the property is violated because the automaton remains in the acceptance state 0.

## FLTL: Weak Until W

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The linear temporal logic formula  $p \text{ W } q$  -  $p$  weak until  $q$  - is true if and only if  $p$  is true indefinitely or if  $p \text{ U } q$ .

`assert POLITE = (!enter W knock)`

- ◆ We should not enter a room before knocking.
- ◆ It does not mandate that knock will eventually happens.
- ◆ The proposition is a safety property.

## Definitions

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- ◆ always [], eventually  $\langle \rangle$  and weak until  $W$  can be simulated by until  $U$ :
  - $\langle \rangle p \equiv \text{true } U \ p$
  - $[]p \equiv !\langle \rangle !p$
  - $p \ W \ q \equiv []p \ || \ (p \ U \ q)$
- ◆ FLTL allows boolean expressions of constants and parameters.
  - `assert true = rigid(1)`
  - `assert false = rigid(0)`
  - `rigid(0)` and `rigid(1)` are fluent propositions that do not change truth value with the passage of time as measured by the occurrence of events.

## FLTL: Next time X

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The linear temporal logic formula  $X p$  - next  $p$  - is true if and only if  $p$  is true at the next instant.

- ◆ By next instant, we mean when the next action occurs - this includes silent actions.

`assert SEQ = (a && X b && X X c)`

- ◆ The proposition requires that the system executes  $a$  in the initial instance, which is immediately followed by  $b$  and then  $c$ .

## Summary

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- ◆ A fluent is defined by a set of initiating actions and a set of terminating actions.
- ◆ At a particular instant, a fluent is true if and only if it was initially true or an initiating action has previously occurred and, in both cases, no terminating action has yet occurred.
- ◆ In general, we don't differentiate safety and liveness properties in linear temporal logic.
- ◆ We verify an LTS model against a given set of fluent propositions.
- ◆ LTSA evaluates the set of fluents that hold each time an action has taken place in the model.



## Course Outline

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2. Processes and Threads
3. Concurrent Execution
4. Shared Objects & Interference
5. Monitors & Condition Synchronization
6. Deadlock
7. Safety and Liveness Properties
8. Model-based Design

*The main basic*  
**Concepts**  
**Models**  
**Practice**

### *Advanced topics ...*

- |                                       |                               |
|---------------------------------------|-------------------------------|
| 9. <b>Dynamic systems</b>             | 12. <b>Timed Systems</b>      |
| 10. Message Passing                   | 13. Program Verification      |
| 11. Concurrent Software Architectures | 14. <b>Logical Properties</b> |