

Nonblocking Communications

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SE/CS 4F03
February 2016

Outline

Introduction

MPI_Isend

MPI_Irecv

Wait routines

Example

Final remarks

Introduction

- ▶ Nonblocking communications are useful for overlapping communication with computation
That is, compute while communicating data
- ▶ A nonblocking operation requests the MPI library to perform an operation: when it can
- ▶ Nonblocking operations do not wait for any communication events to complete
- ▶ Nonblocking send and receive: return almost immediately
- ▶ The user can modify a send [resp. receive] buffer only after send [resp. receive] is completed
- ▶ There are “wait” routines to figure out when a nonblocking operation is done

MPI_Isend

Performs a nonblocking send

```
int MPI_Isend(void* buf, int count, MPI_Datatype datatype, int dest  
, int tag, MPI_Comm comm, MPI_Request *request)
```

buf	starting address of buffer
count	number of entries in buffer
datatype	data type of buffer
dest	rank of destination
tag	message tag
comm	communicator
request	communication request (out)

MPI_Irecv

Performs a nonblocking receive

```
int MPI_Irecv(void* buf, int count, MPI_Datatype datatype, int source, int tag, MPI_Comm comm, MPI_Request *request)
```

buf	starting address of buffer (out)
count	number of entries in buffer
datatype	data type of buffer
source	rank of source
tag	message tag
comm	communicator
request	communication request (out)

Wait routines

```
int MPI_Wait (MPI_Request *request, MPI_Status *status)
```

Waits for MPI_Isend or MPI_Irecv to complete

request request (in), which is out parameter in MPI_Isend and
MPI_Irecv

status status (out)

MPI_Waitall

waits for all given communications to complete

MPI_Waitany

waits for any of given communications to complete

MPI_Test

tests for completion of send or receive

MPI_Testany

tests for completion of any previously initiated communication

Example

From http://www.llnl.gov/computing/tutorials/mpi/samples/C/mpi_ringtopo.c

```
/* nonb.c */
#include <stdio.h>
#include "mpi.h"

int main (int argc, char *argv[])
{
    int numtasks, rank, next, prev, buf[2],
        tag1=1, tag2=2;
    MPI_Request reqs[4];
    MPI_Status stats[4];

    MPI_Init (&argc,&argv);
    MPI_Comm_size (MPI_COMM_WORLD, &numtasks);
    MPI_Comm_rank (MPI_COMM_WORLD, &rank);
```

```
prev = rank-1;    next = rank+1;

if (rank == 0)                  prev = numtasks - 1;
if (rank == (numtasks - 1))   next = 0;

MPI_Irecv(&buf[0], 1, MPI_INT, prev, tag1, MPI_COMM_WORLD, &
          reqs[0]);
MPI_Irecv(&buf[1], 1, MPI_INT, next, tag2, MPI_COMM_WORLD, &
          reqs[1]);

MPI_Isend(&rank, 1, MPI_INT, prev, tag2, MPI_COMM_WORLD, &reqs
          [2]);
MPI_Isend(&rank, 1, MPI_INT, next, tag1, MPI_COMM_WORLD, &reqs
          [3]);

MPI_Waitall(4, reqs, stats);
printf("Task %d communicated with tasks %d & %d\n", rank, prev,
       next);

MPI_Finalize();
}
```

Final remarks

- ▶ Nonblocking send can be posted whether a matching receive has been posted or not
- ▶ Send is completed when data has been copied out of send buffer
- ▶ Nonblocking send can be matched with blocking receive and vice versa
- ▶ Communications are initiated by sender
- ▶ A communication will generally have lower overhead if a receive buffer is already posted when a sender initiates a communication