

Application of the LLL Algorithm in Sphere Decoding

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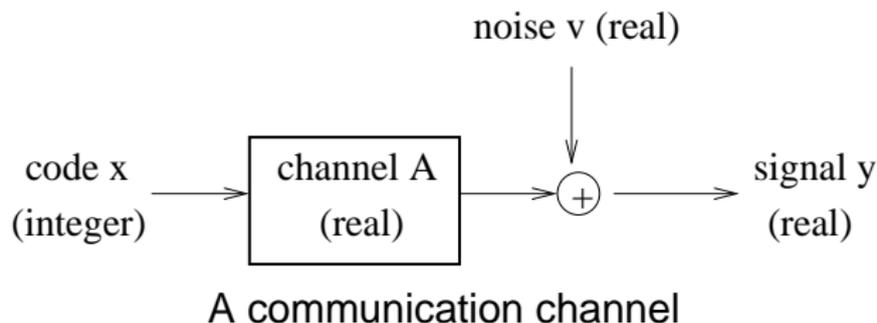
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Outline

- 1 Introduction
 - Application
 - Integer Least Squares
- 2 Sphere Decoding
 - Reducing Dimension
 - Searching Lattice Points
 - Choosing a Radius
- 3 The LLL Algorithm
- 4 Conclusion

Application



x : code vector, integer

A : channel matrix, real

y : received signal, $y = Ax + v$

$$\min_{x \in \mathbb{Z}^m} \|Ax - y\|_2^2$$

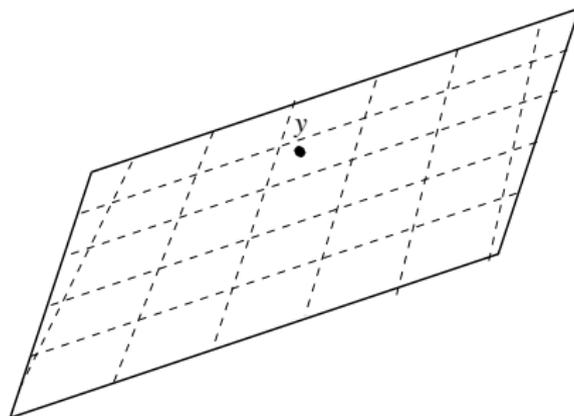
Integer Least Squares

$$\min_{x \in \mathbb{Z}^m} \|Ax - y\|_2^2$$

A : Generating matrix, n -by- m , $n \geq m$, real

y : n -vector, real

x : m -vector, solution, **integer**



A Naive Approach

A seemingly simple approach, Babai solution

$$\mathbf{x} = \lceil A^\dagger \mathbf{y} \rceil$$

Example

$$A = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix} \quad \mathbf{y} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

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Example

$$\mathbf{A} = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix} \quad \mathbf{y} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

real LS solution $\begin{bmatrix} -0.3333 \\ 0.3333 \end{bmatrix}$ rounded to $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$,

giving residual $\|\mathbf{Ax} - \mathbf{y}\|_2 = \sqrt{3}$.

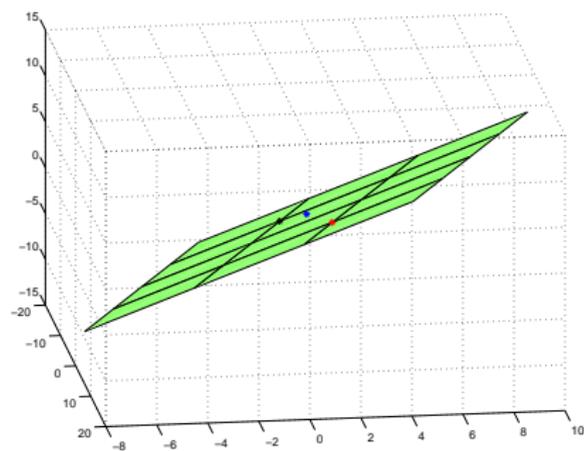
A Naive Approach (cont.)

The integer least squares solution

$$x = \begin{bmatrix} -2 \\ 1 \end{bmatrix},$$

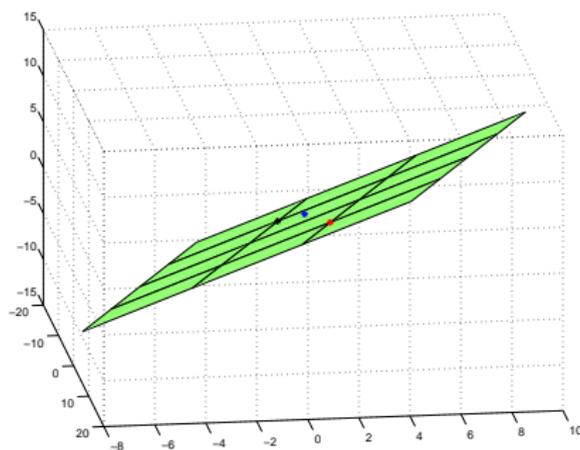
giving residual $\|Ax - y\|_2 = \sqrt{2}$.

Graph



A graph of the naive approach

Graph



A graph of the naive approach

In general, integer least squares problem is non-polynomial (NP) hard.

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Problem Setting

- 1 Search for all lattice points inside the sphere

$$\|Ax - y\|_2 \leq \rho$$

of radius ρ .

- 2 Among the lattice points inside the sphere, find the one that minimizes $\|Ax - y\|_2$.

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Choosing a radius ρ

- Too large, too many lattice points inside sphere, expensive
- Too small, no lattices points inside sphere

Reducing Dimension

QR decomposition

$$A = [Q_1 \quad Q_2] \begin{bmatrix} R \\ 0 \end{bmatrix}$$

$[Q_1 \quad Q_2]$: orthogonal

R : upper triangular, m -by- m

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Then

$$\|Ax - y\|_2^2 = \|Rx - Q_1^T y\|_2^2 + \|Q_2^T y\|_2^2$$

Reducing Dimension (cont.)

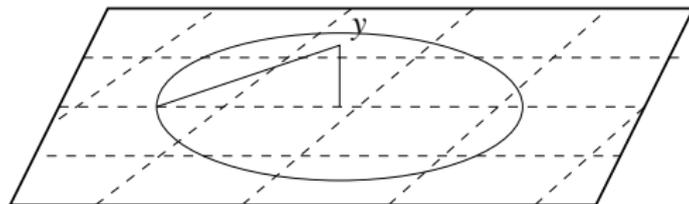
$$\|Ax - y\|_2^2 \leq \rho^2$$

becomes the triangular ILS problem:

$$\|Rx - \hat{y}\|_2^2 \leq \hat{\rho}^2$$

$$\hat{y} = Q_1^T y$$

$$\hat{\rho}^2 = \rho^2 - \|Q_2^T y\|_2^2$$



Searching

Partition

$$Rx - \hat{y} = \begin{bmatrix} R_{1:m-1,1:m-1} & r_{1:m-1,m} \\ 0 & r_{m,m} \end{bmatrix} \begin{bmatrix} x_{1:m-1} \\ x_m \end{bmatrix} - \begin{bmatrix} \hat{y}_{1:m-1} \\ \hat{y}_m \end{bmatrix}$$

Searching

Partition

$$R\mathbf{x} - \hat{\mathbf{y}} = \begin{bmatrix} R_{1:m-1,1:m-1} & r_{1:m-1,m} \\ 0 & r_{m,m} \end{bmatrix} \begin{bmatrix} \mathbf{x}_{1:m-1} \\ x_m \end{bmatrix} - \begin{bmatrix} \hat{\mathbf{y}}_{1:m-1} \\ \hat{y}_m \end{bmatrix}$$

$$\begin{aligned} \|R\mathbf{x} - \hat{\mathbf{y}}\|_2^2 &= \|R_{1:m-1,1:m-1}\mathbf{x}_{1:m-1} - (\hat{\mathbf{y}}_{1:m-1} - x_m r_{1:m-1,m})\|_2^2 \\ &\quad + (r_{m,m}x_m - \hat{y}_m)^2 \\ &\leq \hat{\rho}^2 \end{aligned}$$

Searching (cont.)

Two necessary conditions:

- 1 $|r_{m,m}x_m - \hat{y}_m| \leq \hat{\rho}$
- 2 $\|R_{1:m-1,1:m-1}x_{1:m-1} - (\hat{y}_{1:m-1} - x_m r_{1:m-1,m})\|_2^2 \leq \tilde{\rho}^2,$
 $\tilde{\rho}^2 = \hat{\rho}^2 - (r_{m,m}x_m - \hat{y}_m)^2$

Searching (cont.)

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Sphere decoding:

Find all integers satisfying cond1;

For each integer solve cond2 recursively. (DFS)

Choosing ρ

Hassibi and Vikalo, 2005

In communications

$$y = Ax + v$$

v : white noise, variance σ^2

Given a probability p ,

1. Find α satisfying

$$p = \int_0^{\alpha n/2} \frac{\lambda^{n/2-1}}{\Gamma(n/2)} e^{-\lambda} d\lambda$$

2. $\rho^2 = \alpha n \sigma^2$

Choosing ρ (cont.)

- The solution lies in the sphere of radius ρ with probability p .
- The expected complexity is polynomial, often roughly cubic.
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- The expected complexity is polynomial, often roughly cubic.
- Works well when σ^2 is small.
- Channel matrix A is not taken into consideration (assuming some statistical characteristics).

Choosing ρ (cont.)

We propose:

1. Solve for real LS solution $\hat{\mathbf{x}} = R^{-1}\hat{\mathbf{y}}$
2. $\hat{\rho}^2 = \|R[\hat{\mathbf{x}}] - \hat{\mathbf{y}}\|_2^2$

Choosing ρ (cont.)

We propose:

1. Solve for real LS solution $\hat{x} = R^{-1}\hat{y}$
2. $\hat{\rho}^2 = \|R\lceil\hat{x}\rceil - \hat{y}\|_2^2$

At least one lattice point in sphere, deterministic.
Both $R(A)$ and $\hat{y}(v)$ are taken into account.

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At least one lattice point in sphere, deterministic.
Both $R(A)$ and $\hat{y}(v)$ are taken into account.

Error in the computed $R^{-1}\hat{y}$ must be addresses.

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What is the LLL algorithm?

A.K. Lenstra, H.W. Lenstra, and L. Lovász (1982)

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$$A = QRZ^{-1}$$

Q: orthonormal columns

Z: unimodular, integer, $\det(Z) = \pm 1$

R: upper triangular, reduced

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1. $|r_{i,j}| \leq |r_{i,i}|/2, \quad j > i$

2. $r_{i+1,i+1}^2 \geq \omega r_{i,i}^2 - r_{i,i+1}^2, \quad 0.25 \leq \omega \leq 1$

What is the LLL algorithm? (cont.)

Application:
Cryptography (integer arithmetic)

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Cryptography (integer arithmetic)

Luk and Tracy (2008), floating-point
Integer Gram-Schmidt scheme?

Combination of Givens reflection and integer Gaussian
reduction.

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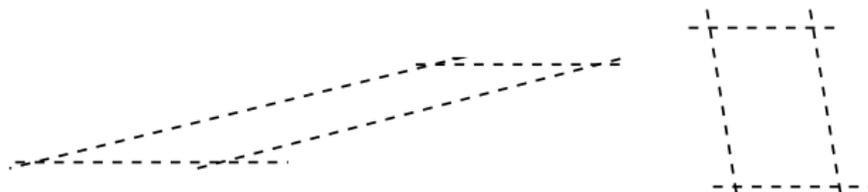
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Luk and SQ (2007), numerical properties

What does the LLL algorithm do?

Example ($\omega = 0.75$)

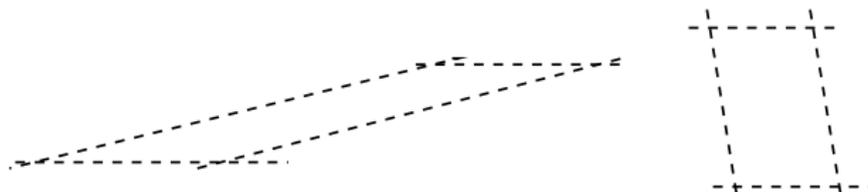
$$\begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix} = QRZ^{-1} = \begin{bmatrix} 2 & -1 \\ 1 & 1 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} -2 & 3 \\ 1 & -1 \end{bmatrix}^{-1}$$



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Making a lattice grid closer to orthogonal.

How may the LLL algorithm help?

Two ways:

Reduce search radius

Reduce the number of search paths

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Example

$$A = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix} \quad \mathbf{b} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

$$\text{ILS solution } \mathbf{z} = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$$

$$\text{distance } \|\mathbf{Az} - \mathbf{b}\|_2 = \sqrt{2}$$

Reducing search radius

QR decomposition

$$R = \begin{bmatrix} 3.7417 & 8.5524 \\ 0 & 1.9640 \end{bmatrix} \quad \hat{\mathbf{b}} = \begin{bmatrix} 1.6036 \\ 0.6547 \end{bmatrix}$$

LLL algorithm ($\omega = 0.75$)

$$\tilde{R} = \begin{bmatrix} 2.2361 & -0.4472 \\ 0 & 3.2864 \end{bmatrix} \quad \tilde{\mathbf{b}} = \begin{bmatrix} 1.3416 \\ 1.0955 \end{bmatrix}$$

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Suppose we use

$$\begin{aligned} \rho &= \|R[R^{-1}\hat{\mathbf{b}}] - \hat{\mathbf{b}}\|_2 \\ \tilde{\rho} &= \|\tilde{R}[\tilde{R}^{-1}\tilde{\mathbf{b}}] - \tilde{\mathbf{b}}\|_2 \end{aligned}$$

as the search radii, then

$$\rho = 1.7321 \quad \text{and} \quad \tilde{\rho} = 1.4142$$

Reducing the number of search paths

$$R = \begin{bmatrix} 3.7417 & 8.5524 \\ 0 & 1.9640 \end{bmatrix} \quad \hat{\mathbf{b}} = \begin{bmatrix} 1.6036 \\ 0.6547 \end{bmatrix}$$

There are two integers $x_2 = 0, 1$ satisfying

$$|r_{2,2}x_2 - \hat{b}_2| \leq \rho (1.7321)$$

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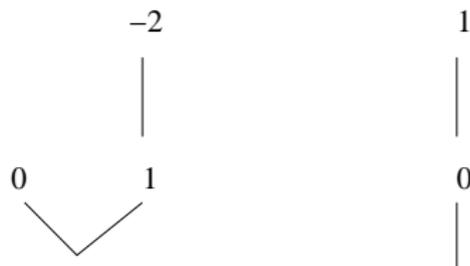
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There is one integer $x_2 = 0$ satisfying

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Even if we use 1.7321 as the radius here, there is still one integer 0.

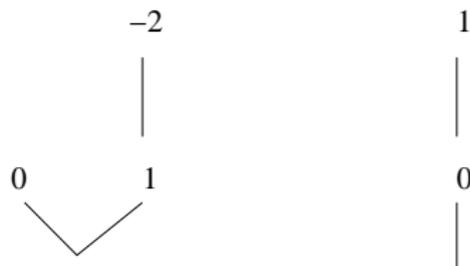
Search trees



$$\tilde{Q}\tilde{R} = RZ, \quad Z = \begin{bmatrix} -2 & 3 \\ 1 & -1 \end{bmatrix}$$

$$\begin{bmatrix} -2 \\ 1 \end{bmatrix} = Z \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

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Reducing the number of search paths in the early stages of a DFS can significantly reduce the total number of search paths.

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Our preliminary experiments show:
The combination of our technique for choosing search radius
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Future work

- complex
- consider computational error in calculating search radius
- extensive experiments on various A and b to investigate numerical behavior

Thank you!

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Questions?