

An Efficient Implementation of Guard-Based Synchronization for an Object-Oriented Programming Language

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Shared Variable Model of Concurrency: ... || ...

Conditional Critical Regions [Hoare 72], e.g. bounded buffer

```
region B: record in, out, n: int; buf: array 0 .. C - 1 of T end
procedure deposit(val: T)
  with B when n < C do
    buf[in] := val; in := (in + 1) mod C; n := n + 1
  guard
  body
procedure fetch() → (val: T)
  with B when count > 0 do
    val := buf[out]; out := (out + 1) mod N; n := n - 1
  atomic
```

Proof Techniques of [Owicki & Gries 76]

```
{P ∧ B} S {Q}
{P} await B then S {Q}
```

atomic

Shared Variable Model of Concurrency: ... || ...

Unity [Chandy & Misra 88], e.g. sorting

```
⟨ ∏ i : 0 ≤ i < N :: A[i], A[i + 1] := A[i + 1], A[i] if A[i] > A[i + 1] ⟶
```

Joint Action Systems [Back & Kurki-Suonio 89]

G → S

TLA [Lamport 94]

G ∧ x' = E

Event-B [Abrial 10]

event e = when G then Q end

CIVL [Siegel et. al 15]

...

→ guards ubiquitous in specification languages

Implementing Guarded Commands

Common wisdom: synchronization by guarded commands cannot be implemented efficiently

"The price that must be paid for this automatic scheme is performance" [Briot, Guerraoui, Lohr 98]

"Conditional critical regions ... expensive to implement ... evaluation [of conditions] results in numerous context switches ... many of which may be unproductive because ... because the condition [may be] false"
[Andrews, Schneider 83]

Semaphores [Dijkstra 62, 67]

```
sem.P = ⟨ sem > 0 → sem := sem - 1 ⟶
sem.V = ⟨ sem := sem + 1 ⟶
```

Monitors [Hoare 74]

```
monitor Buffer
  var in, out, n: int; buf: array 0 .. C - 1 of T
  var nonfull, nonempty: condition
  procedure deposit(val: T)
    while n = C do nonfull.wait
    buf[in] := val; in := (in + 1) mod C; n := n + 1
    nonempty.signal
```

Message Passing [Hoare 78, Occam, Go]

```
var deposit, fetch: channel of T
process Buffer
  var in, out, n: int
  var buf: array 0 .. C - 1 of T
  do n < C & deposit? buf[in] → ...
  | n > 0 & fetch! buf[out] → ...
```

→ an experiment in language restrictions and implementation techniques for atomic guarded commands

Lime: An Action-Based Object-Oriented Programming Language

```
class Buffer
  var in, out, n: int; buf: array 0 .. C - 1 of int
  method deposit(val: int)
    when this.n < C do
      this.buf[this.in] := val; this.in := (this.in + 1) mod C; this.n := this.n + 1
```

synchronization through guards

var b: Buffer

class Producer

```
var p: int
action produce
when true do p := p + 1; b.deposit(p)
```

p := new Producer()

objects are units of concurrency

all objects are concurrent, c.f. Smalltalk, actors

c.f. Seuss [Misra 01]

atomic execution up to method calls

Delayed Doubler: Background Execution

```
class Doubler
  var x: int
  init()
  this.x := 0
  method store(u: int)
    this.x := 2 * u
  method retrieve(): int
    return this.x
```

```
invariant
x mod 2 = 0
refines Doubler
R = d => y = 2 * u
```

Doubler.store



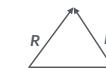
DelayedDoubler.store

Doubler.retrieve



DelayedDoubler.retrieve

```
class DelayedDoubler
  var y:int, d: bool
  init()
  this.y, this.d := 0, true
  method store(u: int)
    this.y, this.d := u, false
  method retrieve(): int
    when this.d do return this.y
  action double
  when not this.d do
    this.y, this.d := 2 * y, true
```

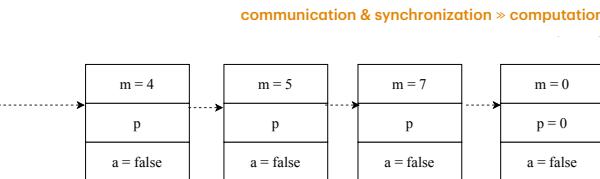


DelayedDoubler.double

c.f. [Bonsangue et al 98]

Priority Queue

```
class PriorityQueue
  var m, p: int
  var l: PriorityQueue
  var a, r: bool
  init()
  l, a, r, m := nil, false, false, 0
  method empty(): bool
    when not r do
      return l = nil
  method add(e: int)
    when not a and not r do
      if l = nil then
        m, l := e, new PriorityQueue()
      else
        p, a := e, true
    method remove(): int
      when not a and not r do
        r := true
        return m
```

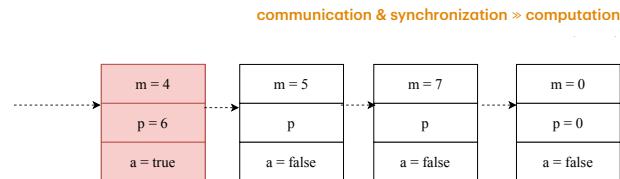


action doAdd
when a do
if m < p then
l.add(p)
else
l.add(m)

action doRemove
when r do
if l = nil then
r := false
return
elif l.empty() then
l := nil
else
m := l.remove()
r := false

Priority Queue

```
class PriorityQueue
  var m, p: int
  var l: PriorityQueue
  var a, r: bool
  init()
  l, a, r, m := nil, false, false, 0
  method empty(): bool
    when not r do
      return l = nil
  method add(e: int)
    when not a and not r do
      if l = nil then
        m, l := e, new PriorityQueue()
      else
        p, a := e, true
  method remove(): int
    when not a and not r do
      r := true
      return m
```



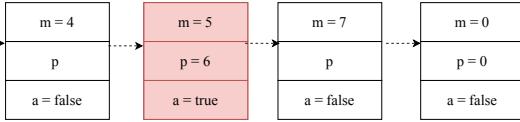
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when r do
if l = nil then
r := false
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elif l.empty() then
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Priority Queue

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  method empty(): bool
    when not r do
      return l = nil
  method add(e: int)
    when not a and not r do
      if l = nil then
        m, l := e, new PriorityQueue()
      else
        p, a := e, true
  method remove(): int
    when not a and not r do
      r := true
      return m
```

communication & synchronization » computation



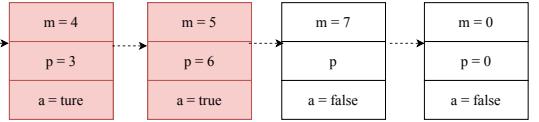
```
action doAdd
when a do
  if m < p then
    l.add(p)
  else
    l.add(m)
    m := p
    a := false
action doRemove
when r do
  if l = nil then
    r := false
  else
    elif l.empty() then
      l := nil
    else
      m := l.remove()
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```

Priority Queue

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  method empty(): bool
    when not r do
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```

```
method add(e: int)
when not a and not r do
  if l = nil then
    m, l := e, new PriorityQueue()
  else
    p, a := e, true
method remove(): int
when not a and not r do
  r := true
  return m
```

communication & synchronization » computation

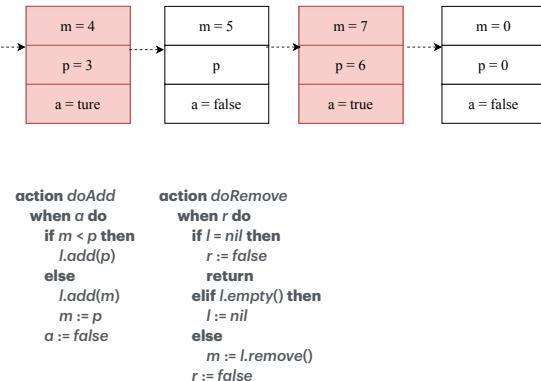


```
action doAdd
when a do
  if m < p then
    l.add(p)
  else
    l.add(m)
    m := p
    a := false
action doRemove
when r do
  if l = nil then
    r := false
  else
    elif l.empty() then
      l := nil
    else
      m := l.remove()
      r := false
```

Priority Queue

```
class PriorityQueue
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  init()
    l, a, r, m := nil, false, false, 0
  method empty(): bool
    when not r do
      return l = nil
  method add(e: int)
    when not a and not r do
      if l = nil then
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  method remove(): int
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communication & synchronization » computation



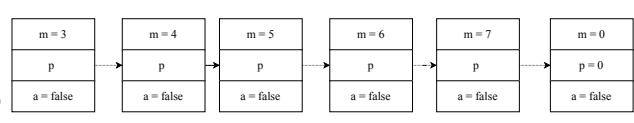
```
action doAdd
when a do
  if m < p then
    l.add(p)
  else
    l.add(m)
    m := p
    a := false
action doRemove
when r do
  if l = nil then
    r := false
  else
    elif l.empty() then
      l := nil
    else
      m := l.remove()
      r := false
```

Priority Queue

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  init()
    l, a, r, m := nil, false, false, 0
  method empty(): bool
    when not r do
      return l = nil
```

```
method add(e: int)
when not a and not r do
  if l = nil then
    m, l := e, new PriorityQueue()
  else
    p, a := e, true
method remove(): int
when not a and not r do
  r := true
  return m
```

communication & synchronization » computation

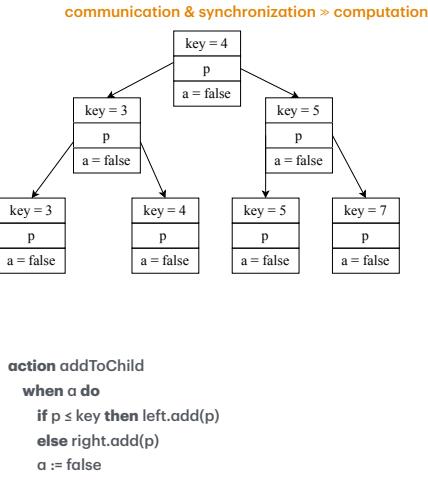


```
action doAdd
when a do
  if m < p then
    l.add(p)
  else
    l.add(m)
    m := p
    a := false
action doRemove
when r do
  if l = nil then
    r := false
  else
    elif l.empty() then
      l := nil
    else
      m := l.remove()
      r := false
```

Leaf-oriented tree

```

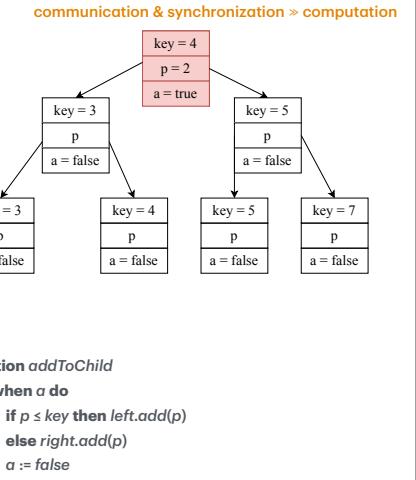
class Node
  var key, p: int
  var left, right: Node
  var a: bool
  init(x: int)
    key, left, right, a := x, nil, nil, false
  method add(x: int)
    when not a do
      if left ≠ nil then a, p := true, x
      elif x < key then
        left, right, key := new Node(x), new Node(key), x
      elif x > key then
        left, right := new Node(key), new Node(x)
    method has(x: int): bool
      when not a do
        if left = nil then return x = key
        elif x ≤ key then return left.has(x)
        else return right.has(x)
  
```



Leaf-oriented tree

```

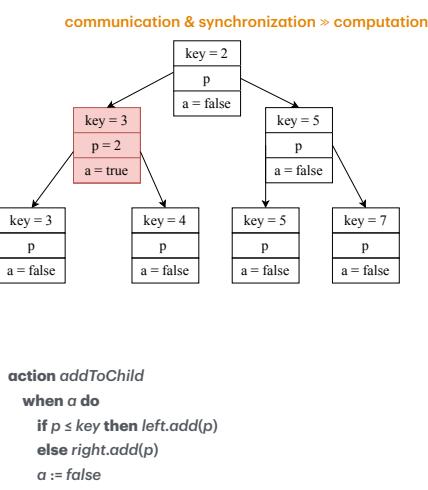
class Node
  var key, p: int
  var left, right: Node
  var a: bool
  init(x: int)
    key, left, right, a := x, nil, nil, false
  method add(x: int)
    when not a do
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Leaf-oriented tree

```

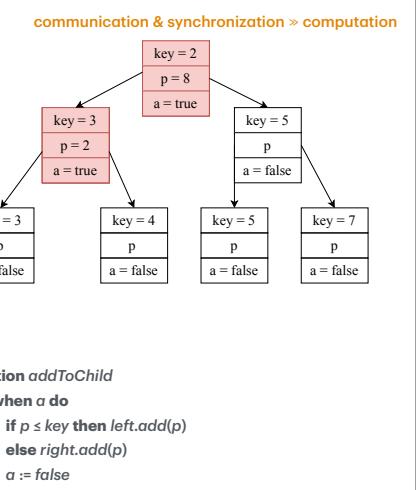
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  var key, p: int
  var left, right: Node
  var a: bool
  init(x: int)
    key, left, right, a := x, nil, nil, false
  method add(x: int)
    when not a do
      if left ≠ nil then a, p := true, x
      elif x < key then
        left, right, key := new Node(x), new Node(key), x
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    method has(x: int): bool
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```



Leaf-oriented tree

```

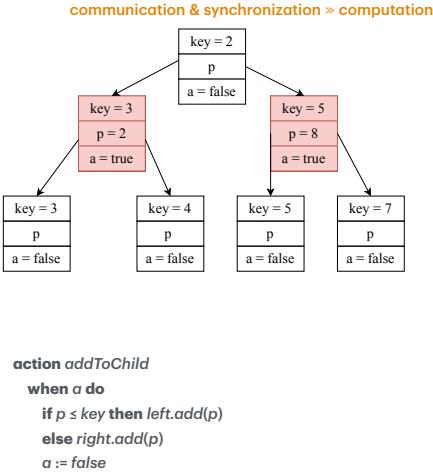
class Node
  var key, p: int
  var left, right: Node
  var a: bool
  init(x: int)
    key, left, right, a := x, nil, nil, false
  method add(x: int)
    when not a do
      if left ≠ nil then a, p := true, x
      elif x < key then
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    method has(x: int): bool
      when not a do
        if left = nil then return x = key
        elif x ≤ key then return left.has(x)
        else return right.has(x)
  
```



Leaf-oriented tree

```

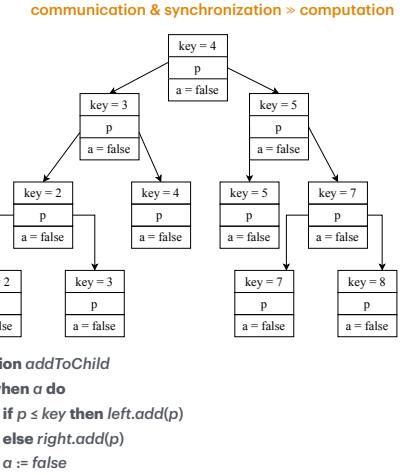
class Node
  var key, p: int
  var left, right: Node
  var a: bool
  init(x: int)
    key, left, right, a := x, nil, nil, false
  method add(x: int)
    when not a do
      if left ≠ nil then a, p := true, x
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Leaf-oriented tree

```

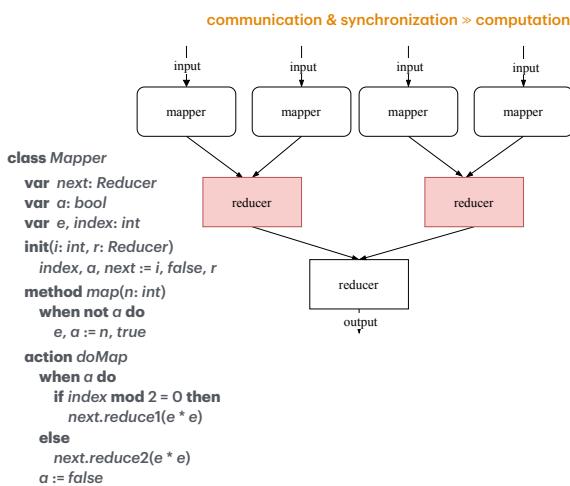
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  method add(x: int)
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    method has(x: int): bool
      when not a do
        if left = nil then return x = key
        elif x ≤ key then return left.has(x)
        else return right.has(x)
  
```



Map-Reduce

```

class Reducer
  var index: int
  var next: Reducer
  var a1, a2: bool
  var e1, e2: int
  init(i: int, r: Reducer)
    index, a1, a2, next := i, false, false, r
  method reduce1(x: int)
    when not a1 do
      e1, a1 := x, true
  method reduce2(x: int)
    when not a2 do
      e2, a2 := x, true
  action doReduce
    when a1 and a2 do
      if index = 1 then
        print(e1 + e2)
        e1, e2 := 0, 0
    elif index mod 2 = 0 then
      next.reduce1(e1 + e2)
    else
      next.reduce2(e1 + e2)
    a1, a2 := false, false
  
```



Formal Definition

By guarded commands with ... || ... and ⟨ ... ⟩, e.g. [Andrews 91]

o.v	= $C_v(o)$
o.m(e)	= $this.lock := false ; C_m(o, e) ; \langle \neg this.lock \rightarrow this.lock := true \rangle$
o := new C(e)	= $o := C_new(e)$
class C	= var C: set(Ref) := {}
var v: V	= var C.lock: Ref → bool
init()	= var C.v: Ref → V
method m(u: U)	= procedure C_new() → (this: Ref)
when g do M	⟨ $this \in C \cup \{nil\}$; $C := C \cup \{this\}$; $this.lock := true$ ⟩ ; I ; $this.lock := false$
...	
action a	= procedure C.m(u: U, this: Ref)
when h do A	⟨ $g \wedge \neg this.lock \rightarrow this.lock := true$ ⟩ ; M ; $this.lock := false$
...	
procedure C.a(this: Ref)	= actions become procedures "called by the scheduler"
⟨ h \wedge \neg this.lock \rightarrow this.lock := true ⟩ ; A	⟨ $h \wedge \neg this.lock \rightarrow this.lock := true$ ⟩ ; A ; $this.lock := false$

fields become functions

methods become procedures

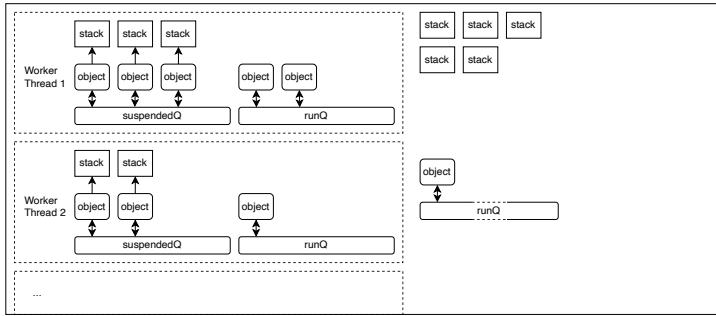
actions become procedures "called by the scheduler"

Program with classes C, ..., Start: nondeterministic choice over all actions

(|| $o \in C \rightarrow C.o()$ || ...) || ... || (var s: Start; s := new Start())

parallel composition over all objects

Runtime Structure



M active objects are mapped to N worker threads (operating system threads)
 For each object with a running action, a coroutine with stack is created
Stack is segmented: initially, only 4 KB; sufficient for most objects; grows as needed
 Coroutines are scheduled cooperatively

Translation Scheme

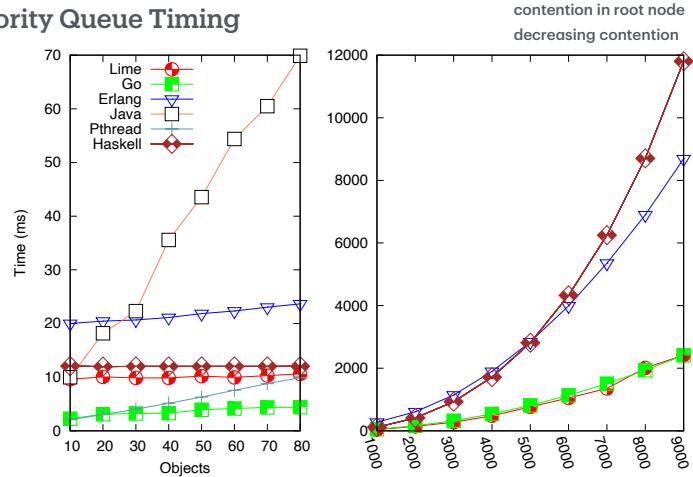
```

o.m() → unlock(this.lock) ; C_m(e, o, originator) ; lock(this.lock)
originator ≈ thread id
every object has field lock

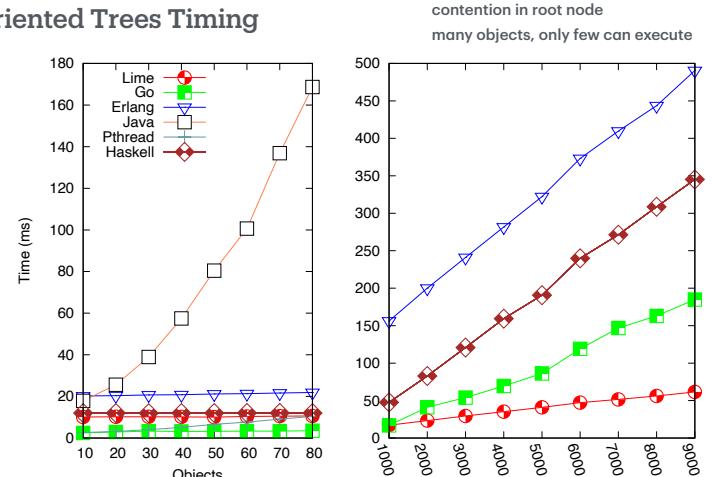
method m(u: U)
  when g do M
  →
procedure C_m(u: U this: Ref, originator: Ref)
  while true do
    if lock(this.lock) then
      if g then
        M
        runQ.put(this)
        unlock(this.lock)
        return
      else
        unlock(this.lock)
        switch_to_sched(originator)
    end
  end

action a
  when h do A
  →
procedure C_a(this: Ref)
  const originator = this
  while true do
    if lock(this.lock) then
      if h then
        A
        unlock(this.lock)
      else
        unlock(this.lock)
        switch_to_sched(originator)
    end
  end
  
```

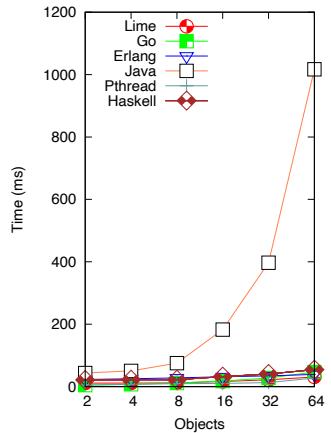
Priority Queue Timing



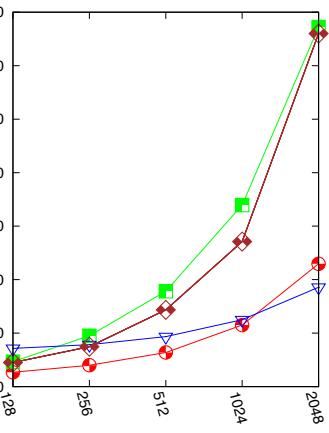
Leaf-oriented Trees Timing



Map-Reduce Timing



contention in last reducer
many objects can execute



Conclusions

Experiment to evaluate language constraints

1. weakening atomicity to atomicity only up to method calls → no need for backtracking
2. guards only over object fields → reevaluated only after call to the object

and implementation techniques

1. allocating for each executing object a small stack that grows as needed
2. each object a user-level coroutine with fast cooperative scheduling (saving only three registers)
3. at most as many worker threads as there are cores
4. combining (lock-free) local and global queues for load balancing and work stealing
5. modifying the procedure call with efficient detection of stack overflow

for atomic guarded commands.

→ Compares favourably with well-established implementations

Details in [Yao20]. Experiments so far only with small programs with simple guards.